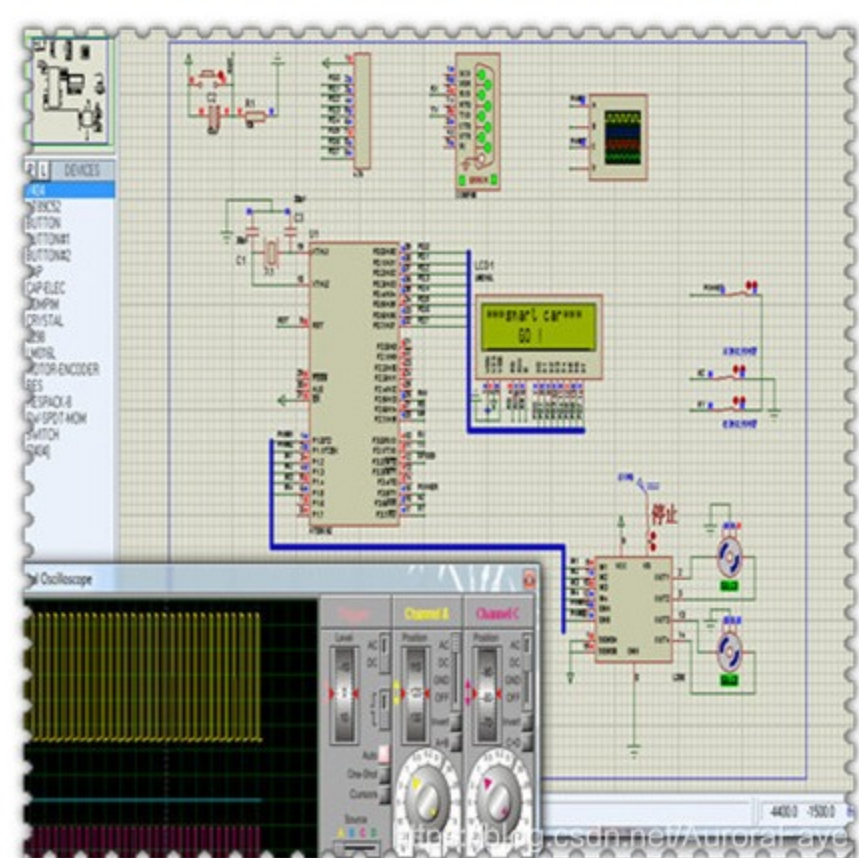




```
1 void right(void)
2 {
3     Pwm_set1(80);
4     Pwm_set2(30);
5     Z1=1;
6     Z2=0;
7     Y1=1;
8     Y2=0;
9     LCD_Str(5,1,"TURN R");
10 }
11 void left(void)
12 {
13     Pwm_set1(30);
14     Pwm_set2(80);
15     Z1=1;
16     Z2=0;
17     Y1=1;
18     Y2=0;
19     LCD_Str(5,1,"TURN L");
20 }
21 void stop(void)
22 {
23     Pwm_set1(0);
24     Pwm_set2(0);
25     Z1=1;
26     Z2=1;
27     Y1=1;
28     Y2=1;
29     LCD_Str(5,1,"stop ");
30     LCD_Str(0,0,"***smart car***");
31 }
32 void xunji(uchar vx)
33 {
34     if( (HZ==0)&&(HY==0) )
35     {
36         go(vx);
37     }
38     else if ( (HZ==1)&&(HY==0) )
39     {
40         left( );
41     }
```