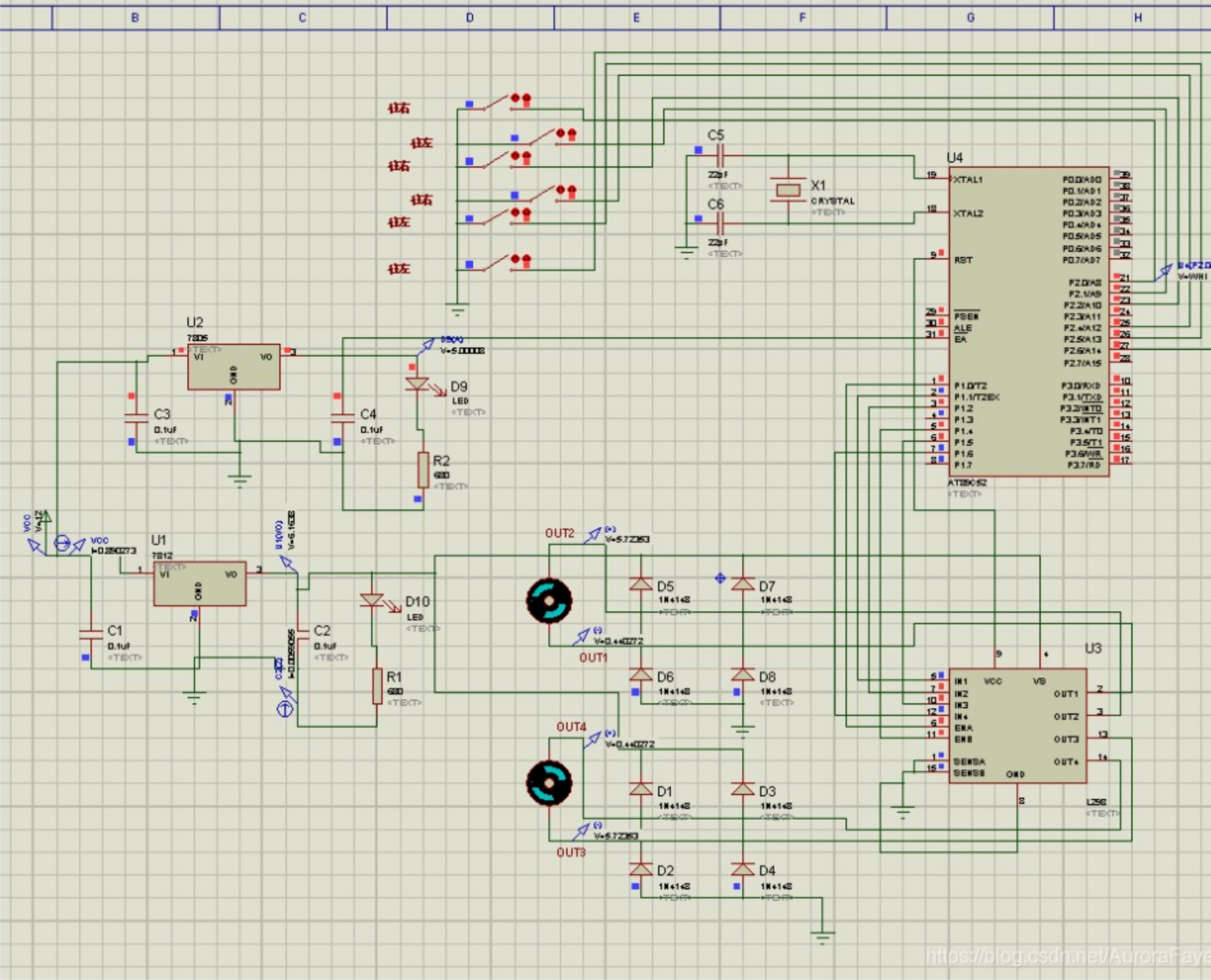
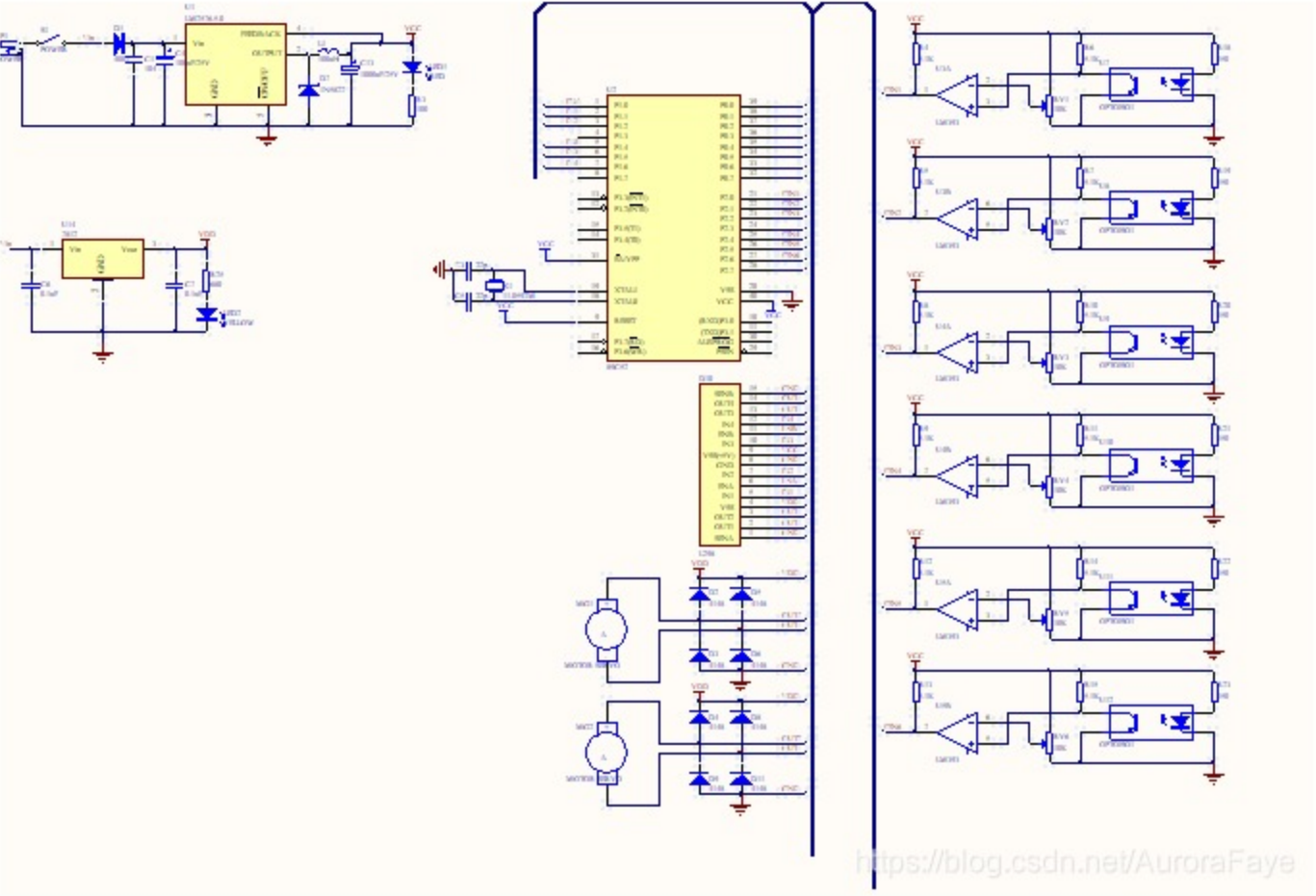




<https://blog.csdn.net/AuroraFaye>



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```
1 #include<reg52.h>
2 #define uchar unsigned char
3 #define uint unsigned int
4 uchar temp,signal,tt1,t0,t1,t2,t3,t4,t5,t6;
5
6
7 void delay_1ms(uint d)
8 {
9     uint i;
10    while(d-->0)
11        for(i=0;i<75;i++);
12 }
13
14 void motor_run()          //电机启动
15 {
16     P1=0x35;
17     delay_1ms(200);
18     P1=0x53;
19     delay_1ms(10);
20 /* ENA=1;
21
22     OUT1=0;
23
24     OUT2=1;
25     delay_1ms(800);
26     OUT2=0;
27     delay_1ms(200);
28
29     ENB=1;
30
31     OUT4=0;
32
33     OUT3=1;
34     delay_1ms(800);
35     OUT3=0;
36     delay_1ms(200);
37 */
38 }
39 void motor_left()         //左进
40 {
41     P1=0x30;
42     delay_1ms(200);
43     P1=0x00;
44     delay_1ms(20);
```

复制