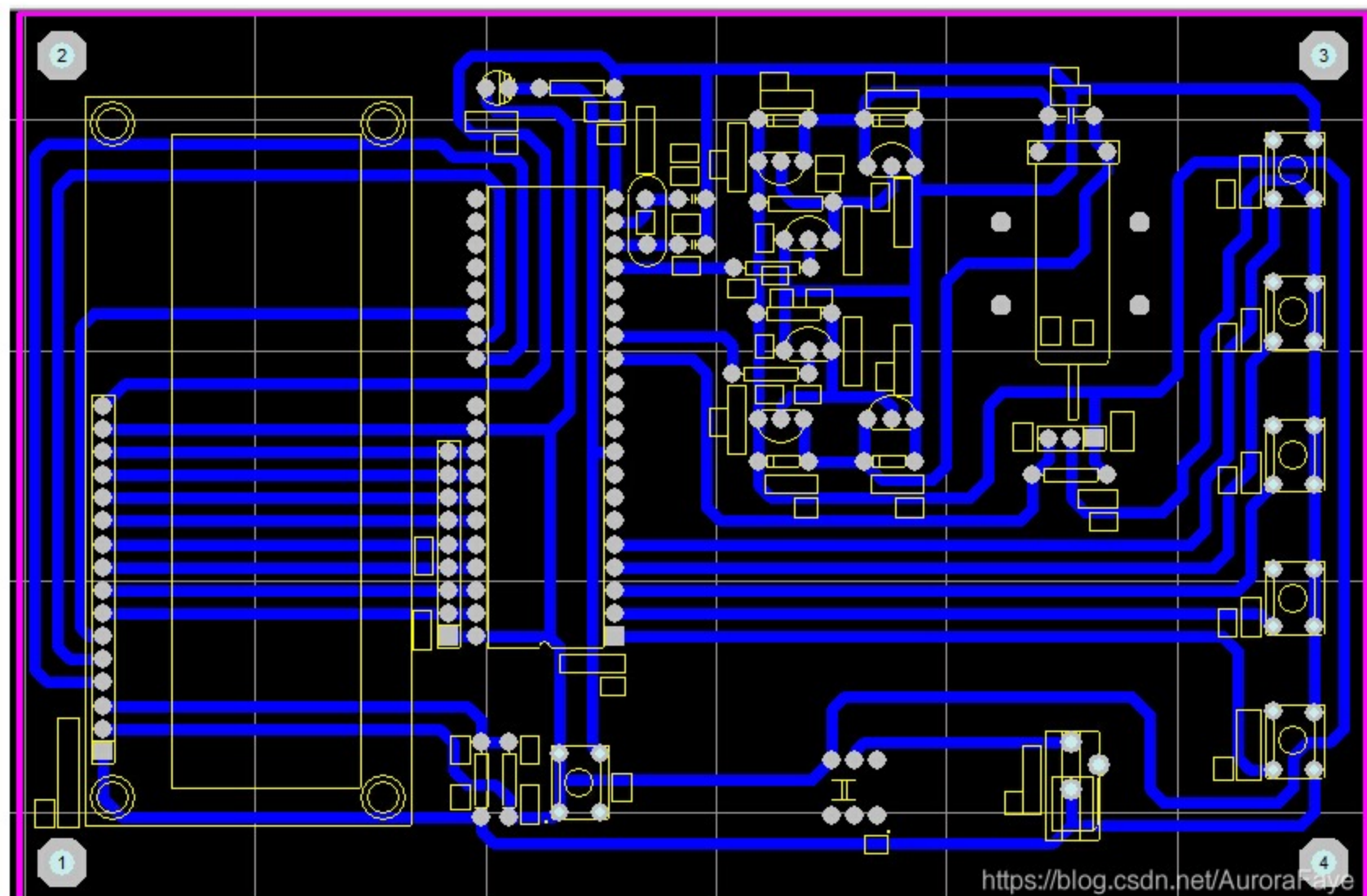
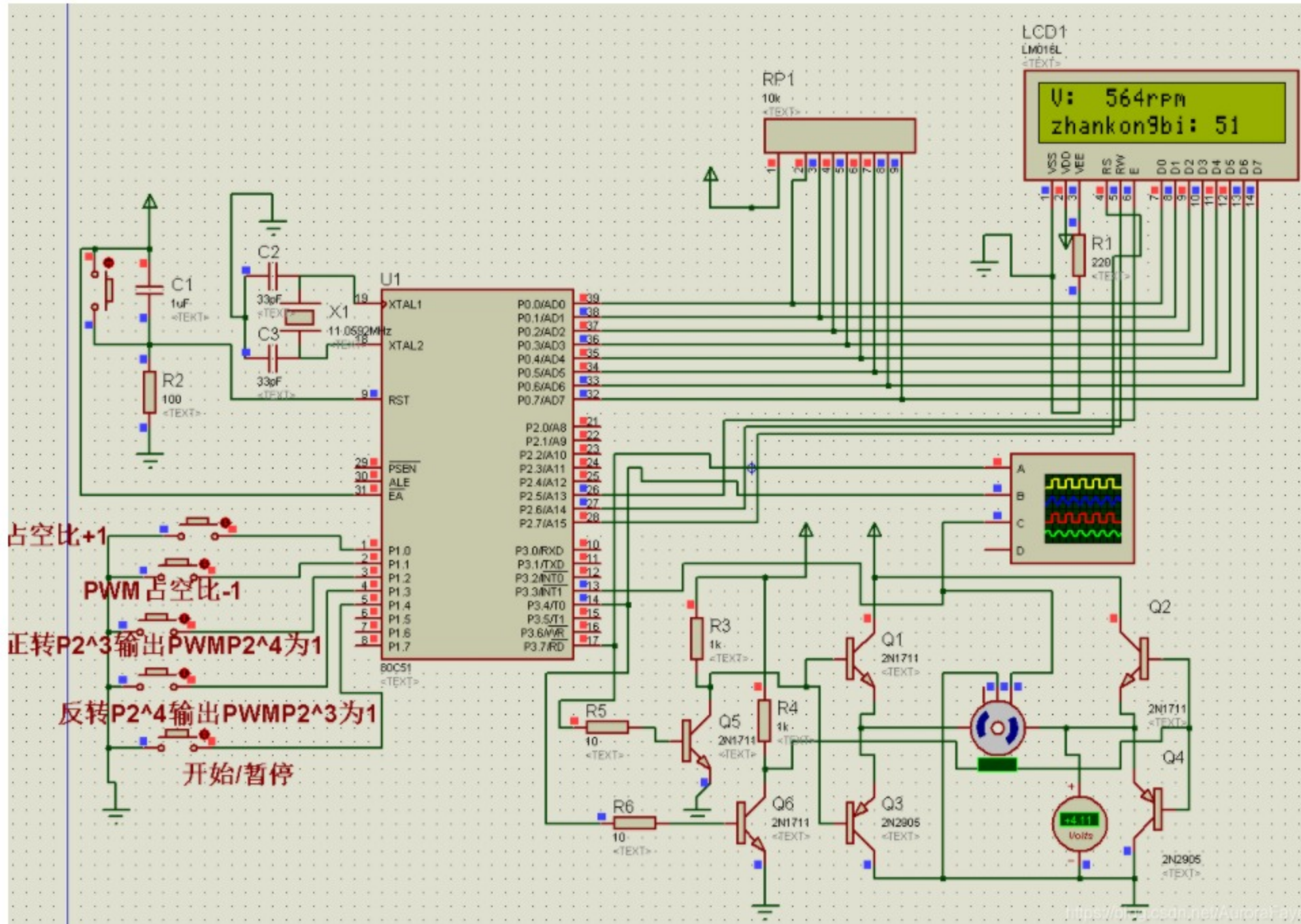




```

1 #include <reg52.h>
2 #define uchar unsigned char
3 #define uint unsigned int
4 void displaym();
5 sbit en=P2^5;           //1602 6管脚
6 sbit rs=P2^7;           //1602端口 4管脚
7 sbit rw=P2^6;           //1602控制端口 5管脚
8 sbit num1=P1^0;         //占空比加1
9 sbit num2=P1^1;         //占空比减一
10 sbit num3=P1^2;        //正传
11 sbit num4=P1^3;        //反转
12 sbit num5=P1^4;        //开始停止切换
13
14 sbit out=P3^4;          //PWM输出用于正传
15 sbit out1=P3^7;        //PWM输出用于反转
16
17 uint zhuan,flag,z1,z2,m,flag_1,zheng,fan,kai;
18
19
20
21
22 void delay(uint z)//延时1ms函数
23 {
24
25     uint x,y;
26     for(x=0;x<z;x++)
27         for(y=0;y<110;y++);
28 }
29
30
31
32 void write_com(uchar com)//向1602写一字节(控制指令)
33 {
34     rs=0;
35     P0=com;
36     delay(5);
37     en=0;
38     delay(10);

```

