

按下仿真按钮后 没有任何反应

按下前进按键 小车全速前进 电机速度（两端电压）大概为69.2

按下后退按键 小车全速后退 电机速度（两端电压）大概为-69.2

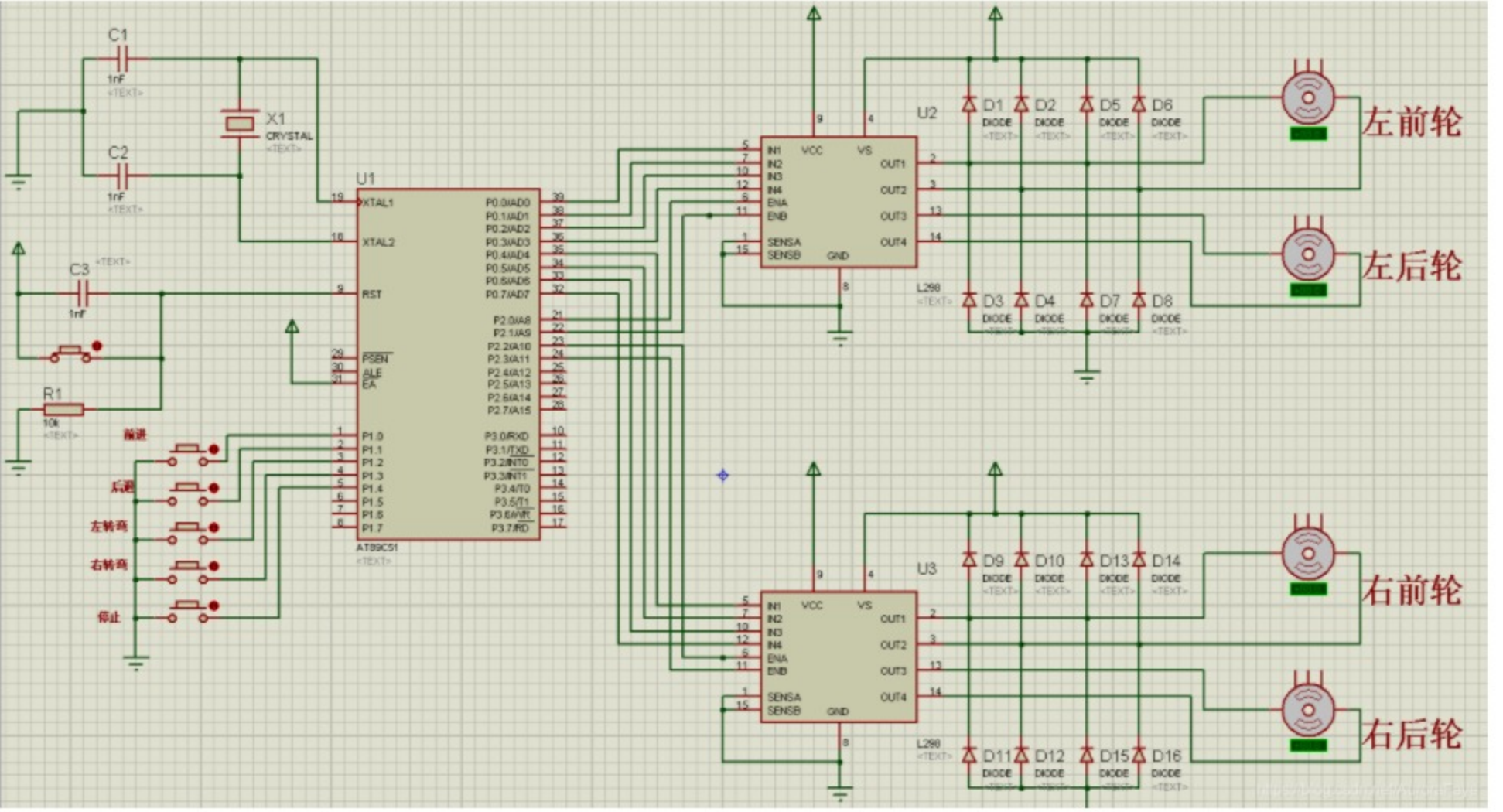
按下左转弯按键 小车主转弯 左前轮左后轮速度（两端电压）大概30左右

右前轮右后轮速度（两端电压）大概50左右

按下右转弯按键 小车主转弯 左前轮左后轮速度（两端电压）大概50左右

右前轮右后轮速度（两端电压）大概30左右

按下停止按键 小车停止



```
1  #include<reg52.h>
2  #define uInt unsigned int
3  #define uChar unsigned char
4
5  #define PWM_MIN_STATE  300
6  #define PWM_MAX_STATE  700
7
8  uInt Time;
9  uInt Time1;
10 uInt Time2;
11 uInt Time3;
12
13 sbit ForwardKey = P1^0;
14 sbit BackKey = P1^1;
15 sbit TurnLeftKey = P1^2;
16 sbit TurnRightKey = P1^3;
17 sbit StopKey = P1^4;
18
19 sbit LeftFront1 = P0^0;
20 sbit LeftFront2 = P0^1;
21 sbit LeftFrontC = P2^0;
22
23 sbit LeftBehind1 = P0^2;
24 sbit LeftBehind2 = P0^3;
25 sbit LeftBehindC = P2^1;
26
27 sbit RightFront1 = P0^4;
28 sbit RightFront2 = P0^5;
29 sbit RightFrontC = P2^2;
30
31 sbit RightBehind1 = P0^6;
32 sbit RightBehind2 = P0^7;
33 sbit RightBehindC = P2^3;
34
35 void DelayMS(uInt t)
36 {
37     uInt i,j;
38     for(i=0;i<t;i++)
39         for(j=0;j<125;j++)
40             ;
41 }
42
43 void CarMove()
44 {
45     LeftFront1=1;
46     LeftFront2=0;
47     LeftFrontC=1;
```

- 51仿真小车程序
- 51仿真小车仿真文件
- 开发资料
- 软件教程
- 注意事项
- 仿真截图.png
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